

Driven Tracer in the Symmetric Exclusion Process: Linear Response and Beyond

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Tracer dynamics in the symmetric exclusion process (SEP), where hard-core particles diffuse on an infinite one-dimensional lattice, is a paradigmatic model of anomalous diffusion. While the equilibrium situation has received a lot of attention, the case where the tracer is driven by an external force, which provides a minimal model of nonequilibrium transport in confined crowded environments, remains largely unexplored. Indeed, the only available analytical results concern the means of both the position of the tracer and the lattice occupation numbers in its frame of reference and higher-order moments but only in the high-density limit. Here, we provide a general hydrodynamic framework that allows us to determine the first cumulants of the bath-tracer correlations and of the tracer's position in function of the driving force, up to quadratic order (beyond linear response). This result constitutes the first determination of the bias dependence of the variance of a driven tracer in the SEP for an arbitrary density. The framework presented here can be applied, beyond the SEP, to more general configurations of a driven tracer in interaction with obstacles in one dimension.

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Introduction.—Single-file transport, corresponding to the diffusion of particles in narrow channels, so that they cannot bypass each other, is observed in various physical, chemical, or biological systems, such as zeolites, colloidal suspensions, or carbon nanotubes [1–4]. In this confined geometry, a tracer displays an anomalous subdiffusive behavior, which has been observed by passive microrheology [1–3]. The symmetric exclusion process (SEP) is a paradigmatic model of such single-file diffusion [5,6], which has been the object of several recent and important developments [7–10]. In this model, particles perform symmetric random walks in continuous time on an infinite one-dimensional lattice, with the constraint that there can only be one particle per site. Characterizing the anomalous dynamics of a tracer in this many-body problem has been the subject of a number of theoretical works [7–9,11–16]. These results are part of a context of intense activity around exact solutions for one-dimensional interacting particle systems [10,17–20].

An important extension of tracer diffusion in the SEP concerns the case where the tracer is submitted to an external driving force [21] (see Fig. 1). This situation is encountered for instance in active microrheology, which is a technique used to probe the properties of living or colloidal systems by forcing the displacement of a tracer through the medium [22,23]. More generally, it constitutes a minimal one-dimensional model for nonequilibrium transport in confined crowded environments, which has received growing attention [24,25] (see also Refs. [26–30]

for related models combining tracer driving and bath-induced crowding). This model allows us to go beyond the usual Gaussian approximation and characterize the non-Gaussian fluctuations, as well as the nonlinear effects of the driving force on the tracer. The only analytical results at arbitrary density concern the means of both the position of the tracer and the lattice occupation numbers in its frame of reference (i.e., the density profiles) [31–33], which have recently been determined also on finite periodic systems [34,35]. Since the seminal works [31–33] that date back almost three decades, the results concerning higher-order cumulants have been limited to the high-density limit [12,36] and to specific situations [37,38]. At arbitrary density, even the determination of the variance of the position of the tracer, which is crucial to quantify its fluctuations, remains a fully open problem.

In this Letter, we fill this gap and provide a general hydrodynamic framework that allows us to determine at long time bath-tracer density profiles and cumulants of the tracer position at linear order in the driving force and at arbitrary density. We also go beyond linear response by

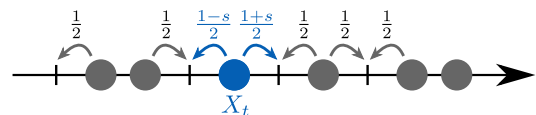


FIG. 1. The SEP with a driven tracer (blue) at position X_t (see the section entitled *Model*).

determining the second cumulant of the tracer position and the corresponding density profile at second order in the driving force. We thus provide the first nontrivial contribution of the driving force to the variance of the tracer position at arbitrary density.

Model.—Each site of an infinite 1D lattice is initially occupied by a particle with probability ρ . Particles perform symmetric continuous-time random walks with half unit jump rate onto each nearest neighbor, and with the hardcore constraint that there is at most one particle per site. A tracer, of position X_t at time t , is initially at the origin, and is the only particle to experience a driving force, which results in asymmetric jump rates, namely $(1+s)/2$ to the right and $(1-s)/2$ to the left. The parameter s quantifies the asymmetry and will be called the bias. The bath particles are described by the set of occupation numbers $\eta_r(t)$ of each site $r \in \mathbb{Z}$ of the lattice at time t , with $\eta_r(t) = 1$ if the site is occupied and $\eta_r(t) = 0$ otherwise.

We first derive the hydrodynamic limit of the problem by extending to the case of a driven tracer the approach we developed to study a symmetric tracer in Refs. [8,9]. We consider the cumulant generating function of the position of the tracer: $\psi(\lambda, t) = \ln \langle e^{\lambda X_t} \rangle = \sum_{n=0}^{\infty} (\lambda^n/n!) \kappa_n$, where the κ_n are the cumulants of the position of the tracer. Its time evolution is deduced from the master equation given in the Supplemental Material (SM) [39] and reads

$$\frac{d\psi}{dt} = \frac{1}{2} \sum_{\nu=\pm 1} [(1+\nu s)(e^{\nu\lambda} - 1)(1-w_\nu)], \quad (1)$$

where we have denoted $w_r(t) = \langle \eta_{X_t+r} e^{\lambda X_t} \rangle / \langle e^{\lambda X_t} \rangle$. We call w_r the generalized density profile generating function, since by expanding it in powers of λ it generates all correlation functions between the displacement of the tracer and the density of bath particles at a distance r from the tracer (represented by the occupation number η_{X_t+r}): $w_r(t) = \sum_{n \geq 0} (\lambda^n/n!) \langle \eta_{X_t+r} X_t^n \rangle_c$, with $\langle \cdots \rangle_c$ the joint cumulants. For instance, at order 1 in λ , $\langle \eta_{X_t+r} X_t \rangle_c = \langle \eta_{X_t+r} X_t \rangle - \langle \eta_{X_t+r} \rangle \langle X_t \rangle$. Beyond controlling the displacement of the tracer [Eq. (1)] and measuring the response of the bath of particles, these profiles w_r are key quantities in the SEP since, in the symmetric case $s = 0$, they satisfy a strikingly simple closed equation [9].

In the hydrodynamic limit of large time and large distances, the different observables have the scalings

$$\psi(\lambda, t) \underset{t \rightarrow \infty}{\simeq} \hat{\psi}(\lambda) \sqrt{2t}, \quad w_r(t) \underset{t \rightarrow \infty}{\simeq} \Phi\left(v = \frac{r}{\sqrt{2t}}\right), \quad (2)$$

where we have omitted the dependency in λ of Φ for simplicity. These scalings have been shown to hold in the symmetric case [7,9,10], and in the biased case [33] at lowest orders in λ for arbitrary density and at all orders in the high-density limit. Here, based on numerical observations, we extend Eq. (2) to all orders in λ . From Eq. (1), these scalings imply the boundary condition:

$$\sum_{\nu=\pm 1} (1+\nu s)(e^{\nu\lambda} - 1)[1 - \Phi(0^\nu)] = 0. \quad (3)$$

Another key boundary condition is obtained from the time evolution of $w_{\pm 1}$ deduced from the master equation [39]:

$$\Phi'(0^\pm) \pm \frac{2\hat{\psi}}{e^{\pm\lambda} - 1} \Phi(0^\pm) = 0. \quad (4)$$

Remarkably, Eq. (4) is closed and does not involve higher-order correlation functions.

In contrast, the bulk equation satisfied by $\Phi(v)$ is not closed. Thus, to compute this profile, we design another approach [45] based on a fluctuating hydrodynamic description.

Macroscopic fluctuation theory (MFT) for a driven tracer.—This approach relies on MFT, which is a powerful tool to treat the stochastic dynamics of diffusive systems at large scale [47], and to determine the statistics of observables in single-file systems such as the current [10,19] or the position of a symmetric tracer [14,15]. The MFT expresses the probability of observing a fluctuation of the macroscopic profile $q(x, t)$, representing the density of particles, in terms of a diffusion coefficient $D(\rho)$ and a mobility $\sigma(\rho)$ characterizing the system at large scales [48]. Below, we mainly focus on the SEP for which $D(\rho) = 1/2$ and $\sigma(\rho) = \rho(1-\rho)$, but the methodology is general. The case of a driven tracer introduces technical difficulties: (i) the driving force experienced by the tracer creates a discontinuity in the MFT fields at the location of the tracer and (ii) the location of this discontinuity is moving with time.

We circumvent these difficulties by mapping the original problem onto a dual problem where the position of the tracer X_t is translated into a flux at the origin Q_t , therefore transforming the moving boundary condition into a static one located at zero [49,50]. A similar approach was used in Ref. [51] for a different model. The dual system is described by new MFT fields \tilde{p} and \tilde{q} , where $\tilde{q}(k, t)$ represents the distance between the particles labeled by the index k , which becomes a continuous variable at the hydrodynamic level considered here. These fields obey the following MFT equations (see SM [39] or Ref. [50] for derivation):

$$\partial_t \tilde{q} = \partial_k [\tilde{D}(\tilde{q}) \partial_k \tilde{q}] - \partial_k [\tilde{\sigma}(\tilde{q}) \partial_k \tilde{p}], \quad (5a)$$

$$\partial_t \tilde{p} = -\tilde{D}(\tilde{q}) \partial_k^2 \tilde{p} - \frac{1}{2} \tilde{\sigma}'(\tilde{q}) (\partial_k \tilde{p})^2, \quad (5b)$$

which involve the transport coefficients of the dual system $\tilde{D}(\tilde{\rho}) = D(1/\tilde{\rho})/\tilde{\rho}^2$ and $\tilde{\sigma}(\tilde{\rho}) = \tilde{\rho}\sigma(1/\tilde{\rho})$. The initial and final conditions are

$$\tilde{p}(k, 0) = \int_{\tilde{\rho}}^{\tilde{q}(k,0)} \frac{2\tilde{D}(z)}{\tilde{\sigma}(z)} dz - \lambda \Theta(k), \quad \tilde{p}(k, 1) = -\lambda \Theta(k), \quad (6)$$

where $\tilde{\rho} = 1/\rho$, and Θ is the Heaviside function. Equations (5) and (6) are the usual MFT equations, completed here by matching conditions at the origin (reminiscent of the position of the tracer in the original system) which implement the bias [52]:

$$\tilde{p}(0^+, t) = \tilde{p}(0^-, t), \quad (7)$$

$$(1-s)\partial_k \tilde{p}(0^+, t) = (1+s)\partial_k \tilde{p}(0^-, t), \quad (8)$$

$$[-\tilde{D}(\tilde{q})\partial_k \tilde{q} + \tilde{\sigma}(\tilde{q})\partial_k \tilde{p}]_0^+ = 0. \quad (9)$$

The first two equations originate from the optimization of the MFT action, and the third one comes from the continuity of the current at the origin. The last matching condition is a consequence of Eq. (3) (see Ref. [39] for details):

$$(1+s)\left(1 - \frac{1}{\tilde{q}(0^+, t)}\right) = (1-s)\left(1 - \frac{1}{\tilde{q}(0^-, t)}\right). \quad (10)$$

Equations (5a)–(10) fully determine the dual MFT fields. Finally, the generalized density profiles of the original tracer problem are obtained from these solutions by

$$\Phi\left(v = \frac{y(k)}{\sqrt{2}}\right) = \frac{1}{\tilde{q}(k, 1)}, \quad y(k) = \int_0^k \tilde{q}(k', 1) dk'. \quad (11)$$

This completely sets the problem of a driven tracer in the SEP. However, since there is *a priori* no explicit solution for arbitrary density and arbitrary bias, this remains formal at this stage. We now go further and propose two lines of investigation of these equations: (i) a numerical resolution for arbitrary sets of parameters and (ii) a perturbative expansion, which yields explicit results valid at *arbitrary* density for the first coefficients $\Phi_n(v)$ defined by the expansion of the hydrodynamic limit of the generalized density profiles: $\Phi(v) = \sum_{n=0}^{\infty} (\lambda^n/n!) \Phi_n(v)$.

Numerical resolution.—We show in Fig. 2 the profiles at order 1 and 2 in λ obtained by the numerical resolution of the MFT equations (see SM [39] for details), which are in perfect agreement with results from microscopic Monte Carlo simulations (see SM [39]), for a broad range of parameters. In particular, we consider strong biases, and densities which are far from the extreme low- and high-density limits. Note that the approach can be extended to the paradigmatic case where the initial density of particles is steplike ($\rho = \rho_+$ in front of the tracer and $\rho = \rho_-$ behind the tracer) [7,20]. Finally, the plots show that our MFT procedure captures nontrivial dependencies of the correlation profiles on the rescaled distance.

Linear order in s .—We first note that, for any bias, at zeroth order in λ , we retrieve the exact results previously obtained for the mean occupation profiles in the frame of reference of the driven tracer [31,33]. However, for the next

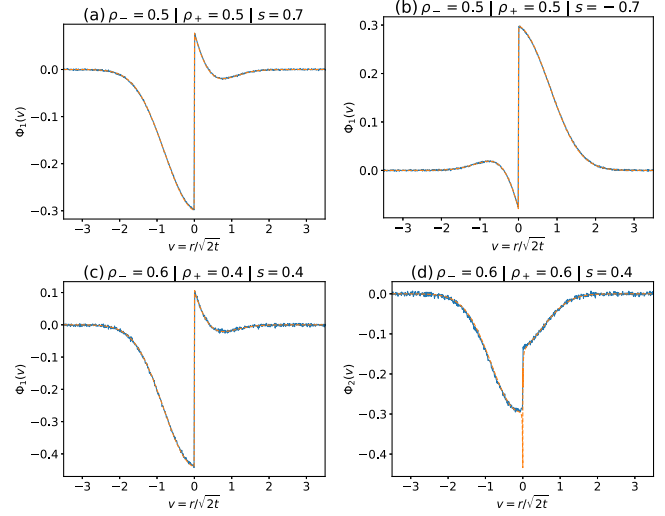


FIG. 2. Profiles Φ_1 and Φ_2 obtained by the numerical resolution of the MFT equations (5a) and (5b) (orange dashed lines), compared to Monte Carlo simulations (blue solid lines), final time 6000, 10^7 simulations for (a)–(c) and 9×10^7 for (d), of the SEP with a driven tracer, for various values of the bias and the density. (a) Φ_1 for $\rho = 0.5$ and $s = 0.7$. (b) Φ_1 for $\rho = 0.5$ and $s = -0.7$. (c) Φ_1 for a step density with $\rho_- = 0.6$, $\rho_+ = 0.4$, and $s = 0.4$. (d) Φ_2 for $\rho = 0.6$ and $s = 0.4$. The discrepancy at $v = 0$ on (d) comes from the numerical errors on Φ_1 near the discontinuity at the origin, which are amplified at the second-order Φ_2 .

orders (Φ_n with $n \geq 1$), no explicit analytical solution of the MFT problem at arbitrary density is available. We then resort to an expansion in powers of the bias s , and define for each order n :

$$\Phi_n(v) = \Phi_n^{(0)}(v) + s\Phi_n^{(1)}(v) + s^2\Phi_n^{(2)}(v) + \dots, \quad (12)$$

where $\Phi_n^{(0)}$ corresponds to the known symmetric case [8,9]. At linear order in the bias s , we find [39,53]

$$\Phi_1^{(1)}(v) = \frac{1-\rho}{2\rho} \left((2-3\rho)\text{erfc}(v) - (1-\rho)\frac{6}{\pi}e^{-v^2} \right), \quad (13)$$

$$\begin{aligned} \Phi_2^{(1)}(v) = & \frac{(1-\rho)[1-2\rho(1-\rho)]}{2\rho^2} \text{erfc}(v) \\ & + \frac{(1-\rho)^2(4-3\rho)}{\pi\rho^2} \text{erfc}(v) - \frac{(1-\rho)^2}{\rho} \text{erfc}\left(\frac{v}{\sqrt{2}}\right)^2 \\ & - \frac{(1-\rho)^2}{2\rho^2} G(\sqrt{2}v) + \frac{8(1-\rho)^3}{\pi^{3/2}\rho^2} v e^{-v^2} \\ & - \frac{4(1-\rho)^2(1-2\rho)}{\pi\rho^2} e^{-v^2} - \frac{(1-\rho)^2}{\pi^{3/2}\rho^2} v e^{-v^2/2} K_0\left(\frac{v^2}{2}\right), \end{aligned} \quad (14)$$

where $G(x) = (1/\pi)\sqrt{2/\pi} \int_x^\infty e^{-z^2/4} K_0(z^2/4) dz$, and K_0 is a modified Bessel function of zeroth order. A key point is

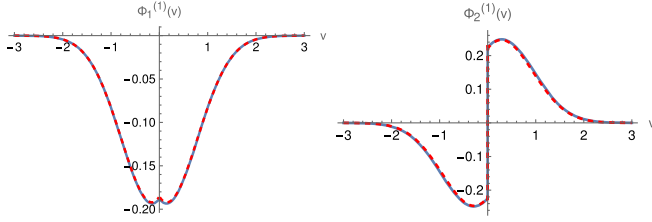


FIG. 3. Generalized density profiles $\Phi_n^{(1)}(v)$ at first order in the bias s , at density $\rho = 0.6$, obtained from the numerical resolution of the MFT equations (5a) and (5b) (dashed red lines), compared to the analytical expressions (13) and (14) (solid blue lines). Left: profile $\Phi_1^{(1)}$. Right: profile $\Phi_2^{(1)}$.

that, contrary to the first order in λ , $\Phi_2^{(1)}$ is a *nonanalytic* function of the rescaled distance v , displaying a logarithmic singularity at the origin. This appears to be a specificity of the driven case, since, in the symmetric case, all Φ_n are analytical functions of the rescaled distance [9]. The functions $\Phi_1^{(1)}(v)$ and $\Phi_2^{(1)}(v)$ are plotted in Fig. 3 and display perfect agreement with the numerical resolution of the MFT equations. The profile $\Phi_1(v)$ measures the correlation between the density at a rescaled distance v from the tracer and the position of the tracer [8]. When there is no driving force, $\Phi_1^{(0)}(v > 0) > 0$; therefore a fluctuation of X_t toward the right is correlated with an increase of the density in front of the tracer, indicating an accumulation of particles in front of the tracer. Here, we find that the linear correction to these correlations due to the presence of the drive $\Phi_1^{(1)}(v)$ is negative, indicating that a positive driving force reduces these correlations, while a negative drive increases them.

In addition to fully characterizing the bath-tracer correlations, the generalized density profiles Φ_n also lead to the cumulants of the tracer's position. This is made possible by the key relation derived above [Eq. (4)]. We get, for $\hat{\kappa}_n \equiv \lim_{t \rightarrow \infty} [\kappa_n / \sqrt{2t}]$,

$$\hat{\kappa}_1 = s \frac{1-\rho}{\rho\sqrt{\pi}} + \mathcal{O}(s^2), \quad \hat{\kappa}_2 = \frac{1-\rho}{\rho\sqrt{\pi}} + \mathcal{O}(s^2), \quad (15)$$

$$\hat{\kappa}_3 = \frac{s}{\pi^{3/2}\rho^3} (1-\rho) \{ (12(1-\rho)^2 - \pi[(8-3\sqrt{2})\rho^2 - 3(4-\sqrt{2})\rho + 3]) \} + \mathcal{O}(s^2). \quad (16)$$

We note that, up to order $n = 3$, $\hat{\kappa}_n = s \hat{\kappa}_{n+1}^{(s=0)} + \mathcal{O}(s^2)$, which implies that

$$\psi(\lambda, t) \underset{t \rightarrow \infty}{\sim} \psi^{(s=0)}(\lambda, t) + s \frac{d\psi^{(s=0)}}{d\lambda} + \mathcal{O}(s^2, \lambda^4). \quad (17)$$

On top of that, we checked from the high-density solution obtained in Refs. [12,36] that, when $\rho \rightarrow 1$, Eq. (17) holds

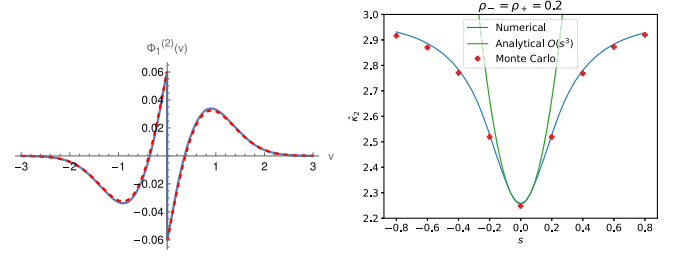


FIG. 4. Left: profile $\Phi_1^{(2)}(v)$ at $\rho = 0.6$ [Eq. (18)] (solid blue lines), compared to the numerical resolution of the MFT equations (5a) and (5b) (dashed red lines). Right: rescaled cumulant $\hat{\kappa}_2$ as a function of the bias s , obtained from the numerical resolution of the MFT equations (5a) and (5b) (solid blue line), compared to the small bias expansion (19) (solid green line). The points are obtained from Monte Carlo simulations (15.8×10^6 simulations, final time 100 000). Note that the correction in s^2 to $\hat{\kappa}_2$ is always positive, for all the values of the density ρ .

at any order in λ , and at arbitrary time. This points toward the generality of this relation.

Beyond linear response.—We next show that explicit analytical results can be obtained beyond linear response which, as we proceed to show, can be quantitatively and even qualitatively significant. In addition, even if our previous expressions provide the leading order in the bias s , they do not bring nontrivial information for even cumulants, since the first nonzero correction to the unbiased case is actually of order s^2 for symmetry reasons. We thus compute the profile Φ_1 at quadratic order in the bias and get [39]

$$\begin{aligned} \Phi_1^{(2)}(v) = & \frac{(1-2\rho)(1-\rho)^2}{2\rho^2} \operatorname{erfc}(v) + \frac{(3-\rho)(1-\rho)^2}{\pi\rho^2} \operatorname{erfc}(v) \\ & - \frac{(1-\rho)^2}{2\rho} \operatorname{erfc}\left(\frac{v}{\sqrt{2}}\right) - \frac{(1-\rho)^2}{2\rho^2} G(\sqrt{2}v) \\ & + \frac{5(1-\rho)^3}{\pi^{3/2}\rho^2} v e^{-v^2} - \frac{(3-5\rho)(1-\rho)^2}{\pi\rho^2} e^{-v^2} \\ & - \frac{(1-\rho)^2}{\pi^{3/2}\rho^2} v e^{-v^2/2} K_0\left(\frac{v^2}{2}\right). \end{aligned} \quad (18)$$

Interestingly, we note that, even at order 1 in λ (and not only at order 2 as in the linear response analysis discussed above), the density profile is in fact nonanalytic at the origin. We stress that this qualitatively different feature emerges *beyond* linear response.

In addition, the expression of $\Phi_1^{(2)}$ yields the s^2 order of $\hat{\kappa}_2 = \hat{\kappa}_2|_{s=0} + s^2 \Delta \hat{\kappa}_2^{(2)} + \mathcal{O}(s^3)$, with

$$\Delta \hat{\kappa}_2^{(2)} = \frac{(1-\rho)^2 \{ 7 - 5\rho - \pi[(\sqrt{2}-3)\rho + 2] \}}{\pi^{3/2}\rho^3}. \quad (19)$$

This result constitutes the first determination of the bias dependence of the variance of a driven tracer in the SEP for

an arbitrary density, a problem which has remained open for more than 25 years.

The function $\Phi_1^{(2)}(v)$ is plotted in Fig. 4 and displays very good agreement with the results obtained from the numerical procedure described above. We also display the dependence of the second cumulant as a function of the bias for a given value of the density $\rho = 0.2$, which shows good agreement with both microscopic Monte Carlo simulations and the numerical resolution as long as the bias is small enough. This cumulant displays an important variation with the bias ($\sim 30\%$), emphasizing the quantitative importance of studying the problem beyond linear response (which gives zero variation).

Conclusion.—In this Letter, starting from microscopic considerations, we built a hydrodynamic framework to study both the dynamics of a driven tracer in the SEP and the response of its environment. This allowed us to determine the first cumulants of bath-tracer correlations and of the tracer position at linear order in the bias and at arbitrary density—a regime of parameters that was left aside so far. We also went beyond linear response by determining the second cumulant and the corresponding correlation profile, therefore unveiling for the first time the dependence of the variance of the tracer’s position on the bias. Importantly, this approach is general and can be extended to study other models of single-file transport, by replacing in Eqs. (5a)–(9) the transport coefficients D and σ by those of the system under consideration, and adapting the matching condition (10) which can be derived from microscopic considerations, as done here for the SEP.

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- [38] The specific situation in Ref. [37] corresponds to the case where the driving force imposed on the tracer is compensated by a step of density resulting in a vanishing mean position.
- [39] See Supplemental Material at <http://link.aps.org/supplemental/10.1103/PhysRevLett.130.020402>, which includes Refs. [40–44], for details on the computations and the numerical procedures.
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